

The background of the slide is a grayscale photograph of a city skyline, likely New York City, featuring a prominent skyscraper (the Freedom Tower) in the center. The skyline is reflected in a body of water in the foreground, creating a symmetrical effect. The text is overlaid on this background.

Migrating to SDN for Mobile Core Networks : A Dynamic and Global Perspective

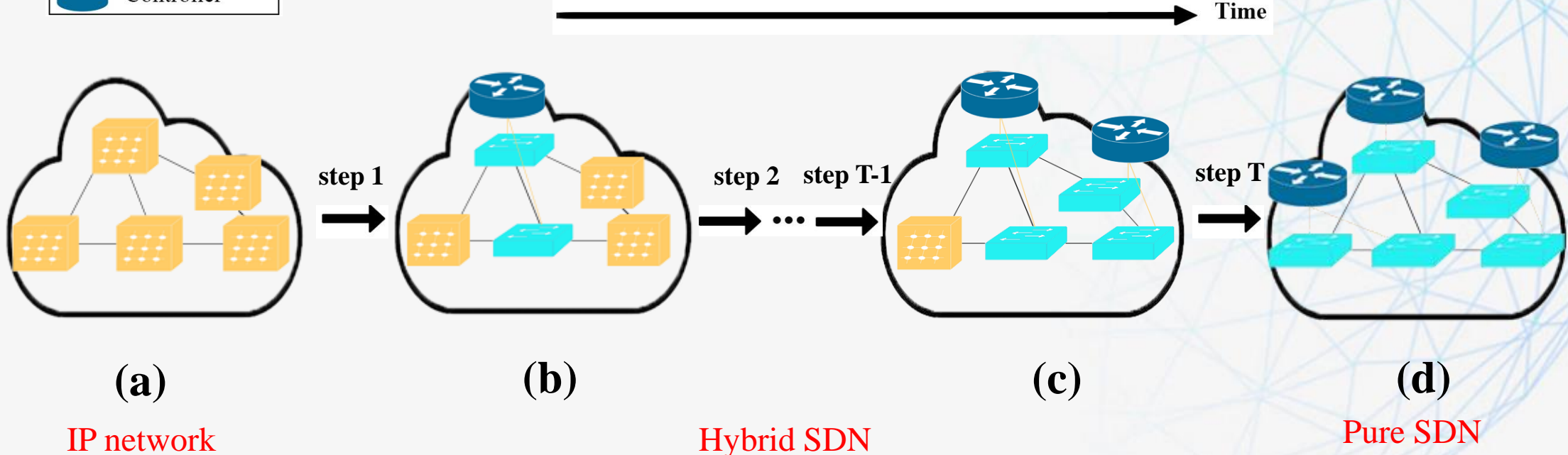
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Background

- Software-Defined Networking SDN
- Hybrid SDN

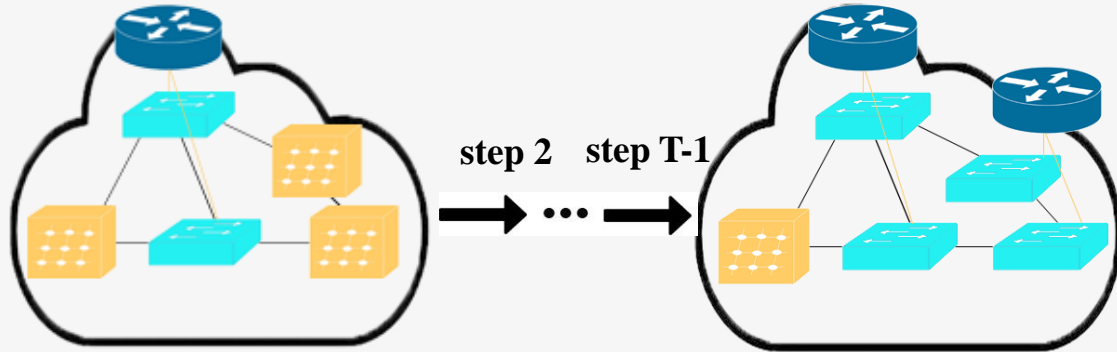


Migrating to SDN



Dynamic

- Considering the entire migration trajectory as a whole
- Only considered switches upgrade



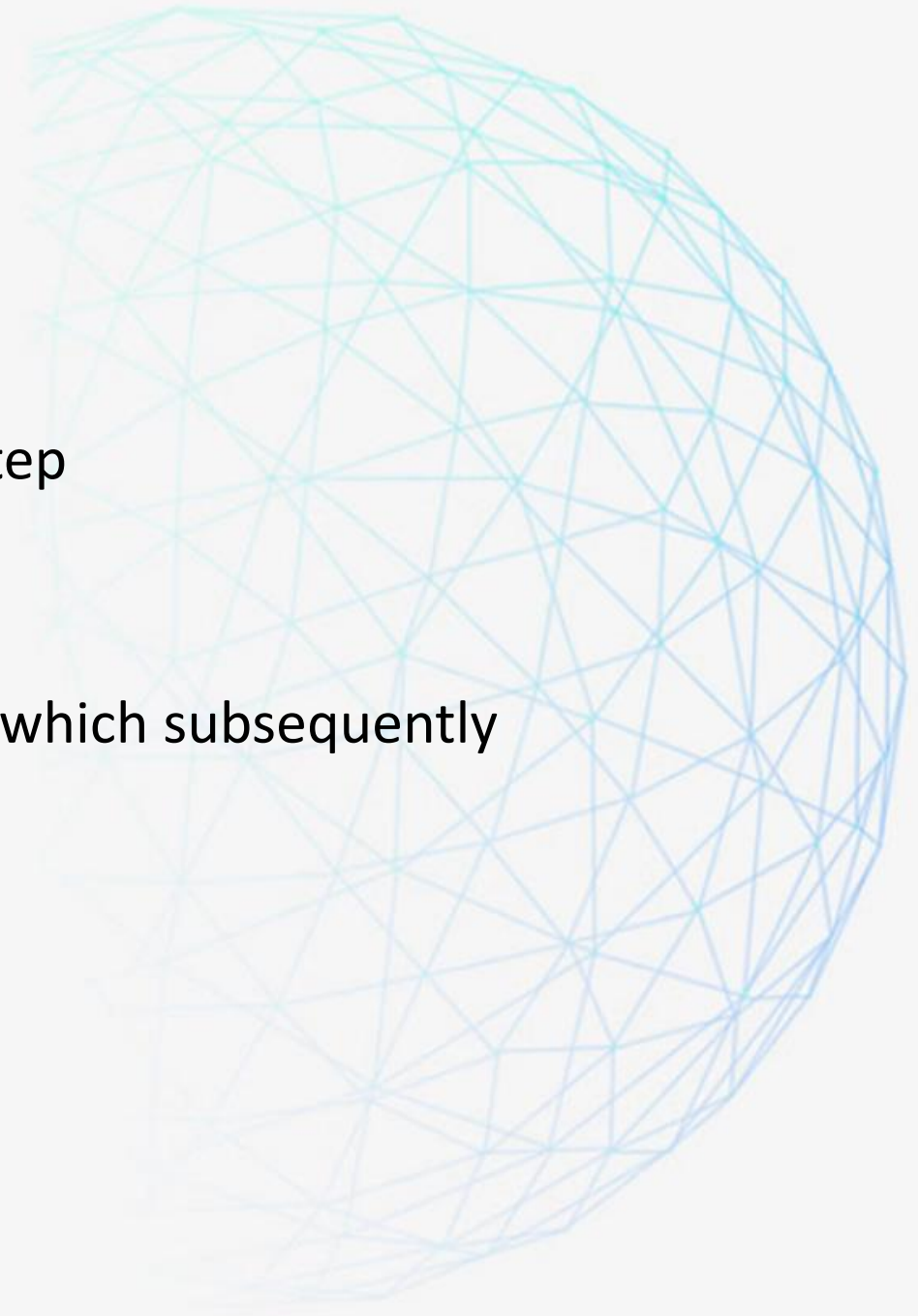
Static

- At a fixed point of time
- Jointly deploy controllers and upgrade switches



Problem

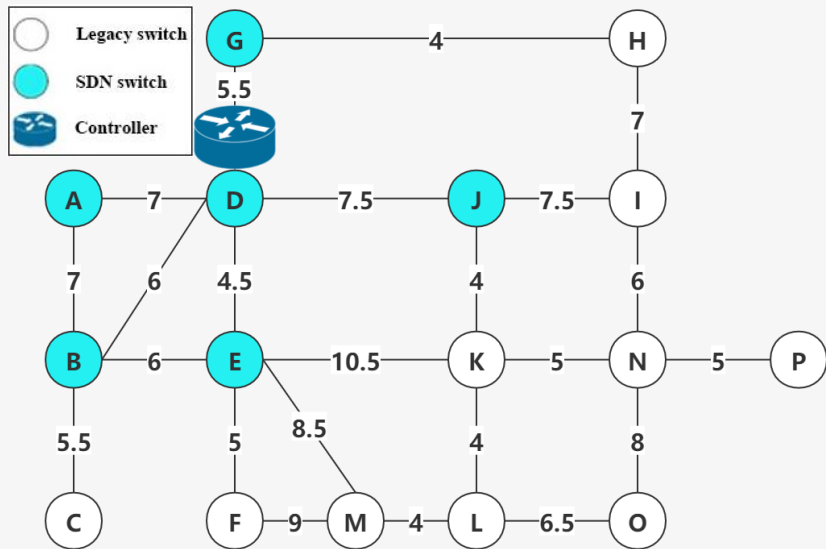
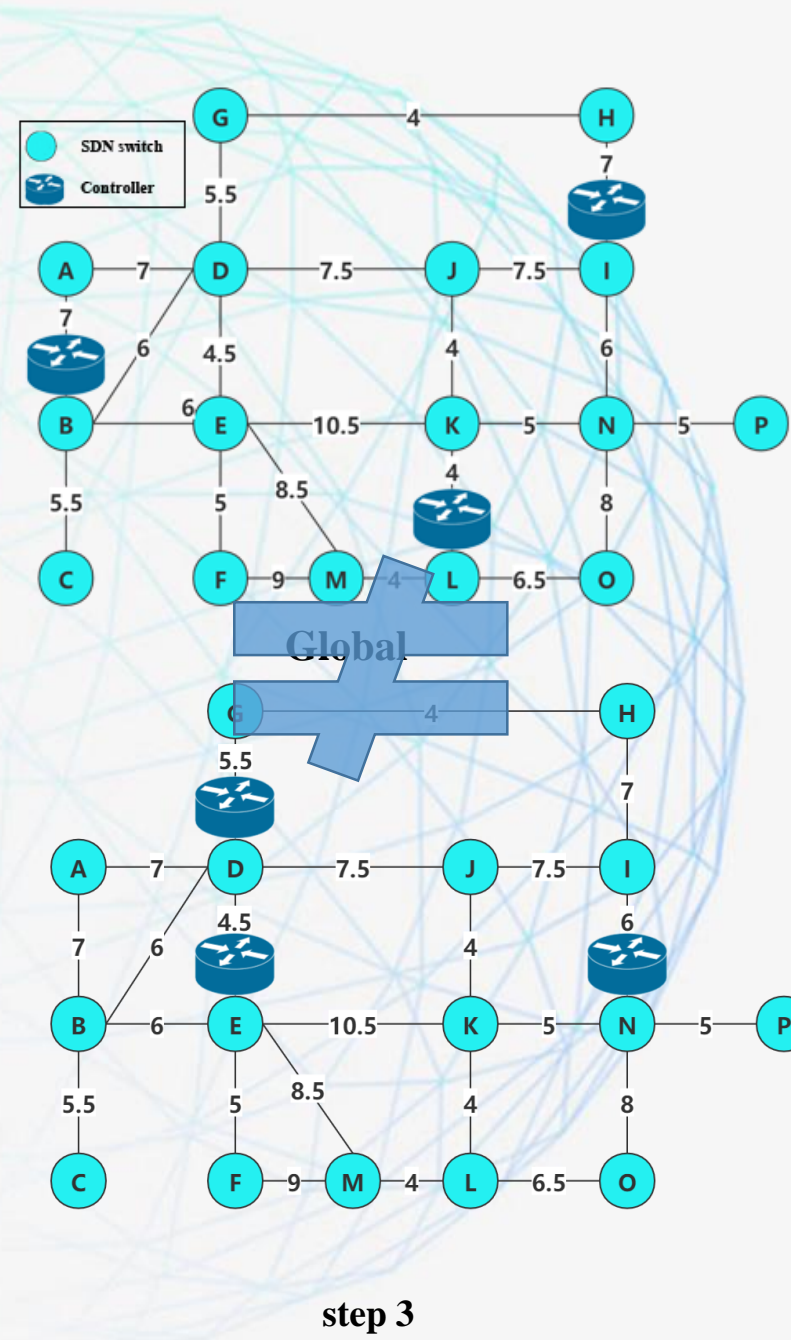
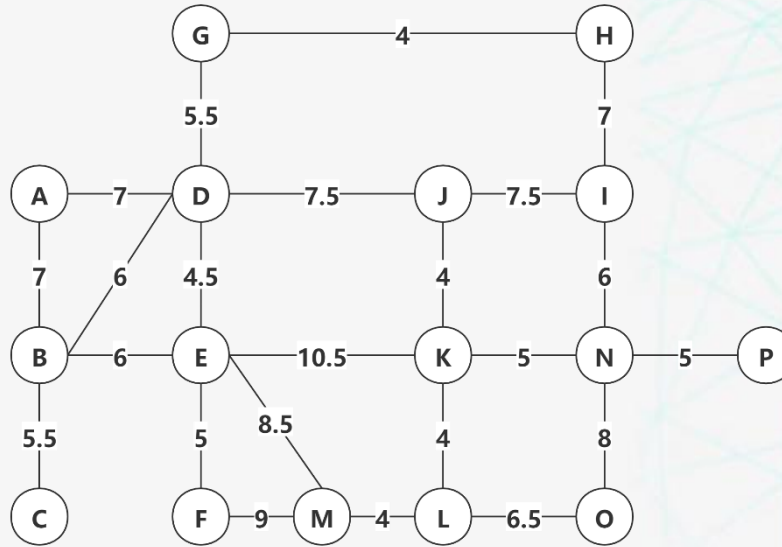
- Which
 - Which legacy devices should upgrade at each step
- When
 - Which legacy devices should upgrade first, and which subsequently
- How
 - Where to deploy controllers
 - Which controller controls which SDN switches



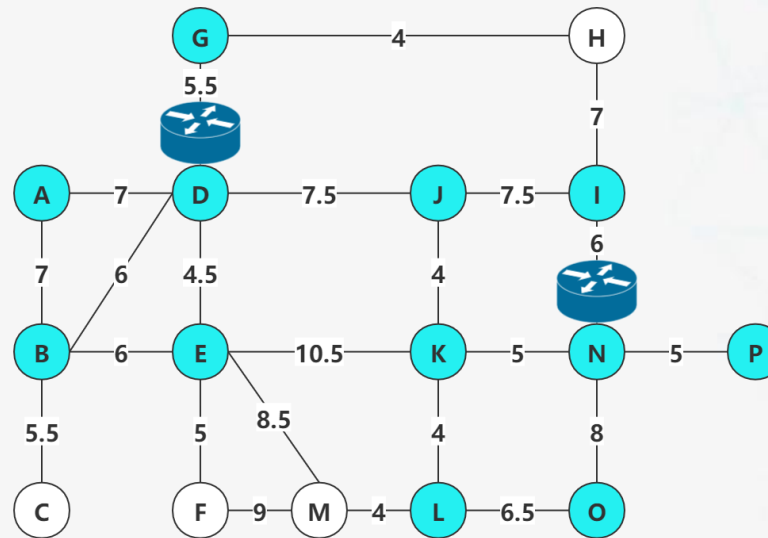
Motivation

Global controllers are on node B, I, L,
with the total delay of **83.5ms**.

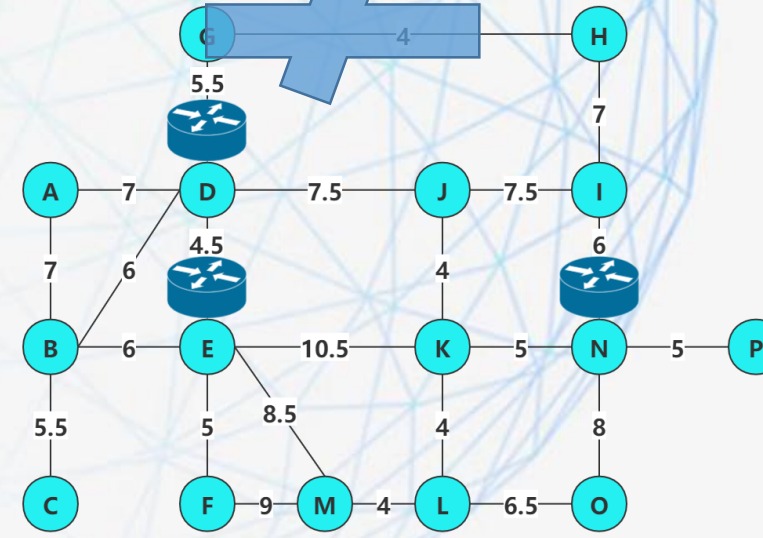
Migration controllers are on node D, E, N,
with the total delay of **93.5ms**.



step 1

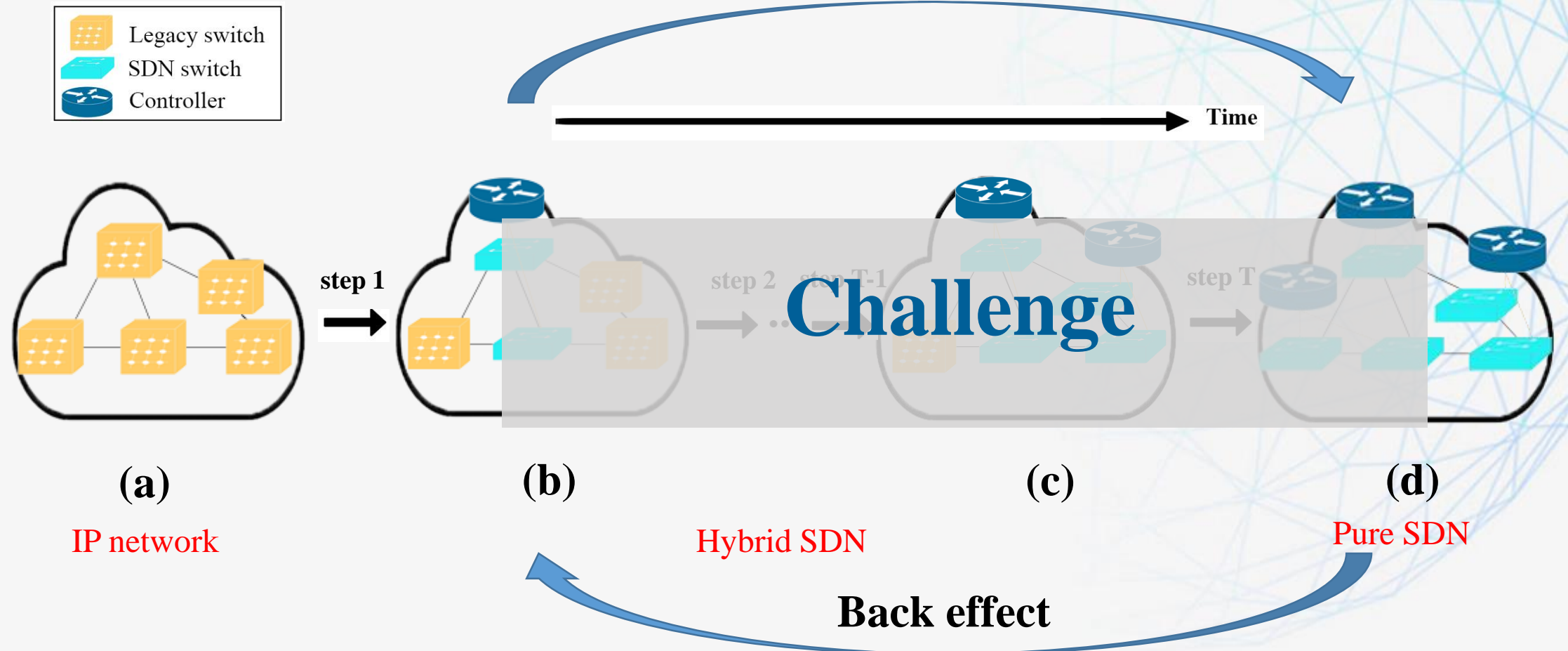


step 2
Local



step 3

Motivation



Model

obj: $\max \sum_{i \in N} \beta^t * d_i * x_i^t$ Upgrade switches

$\min \sum_{i,j \in N} \omega_{ij} * z_{ij}^t$ Deploy controllers

s.t. $\sum_{i \in N} x_i^t = s^t, \sum_t s^t = n,$

$\sum_{i \in N} y_i^t = r^t, \sum_t r^t = m,$

$\sum_{j \in N} z_{ij}^t \leq c * y_i^t,$

$\sum_{i \in N} z_{ij}^t = x_j^t,$

$y_i^t \leq x_i^t,$

$x_i^{t-1} \leq x_i^t,$

$y_i^{t-1} \leq y_i^t,$

$x_i^t, y_i^t, z_{ij}^t \in \{0,1\},$

x_i^t : Upgrade switch i at step t

y_i^t : Deploy controller i at step t

z_{ij}^t : Controller i controls switch j at step t

Maximizing network programmability (1)

Minimizing the delay (2)

$\forall t \in [1, T]$ (3)

$\forall t \in [1, T]$ (4)

$\forall i, \forall t \in [1, T]$ (5)

$\forall j, \forall t \in [1, T]$ (6)

$\forall i, \forall t \in [1, T]$ (7)

$\forall t \in [2, T]$ (8)

$\forall t \in [2, T]$ (9)

$i, j \in N$ (P₁)

Model

Middle steps  **Hybrid SDN**

- Maximizing network programmability
- Minimizing the delay



Hybrid SDN



Accumulation of local optimum may not get the global optimum.

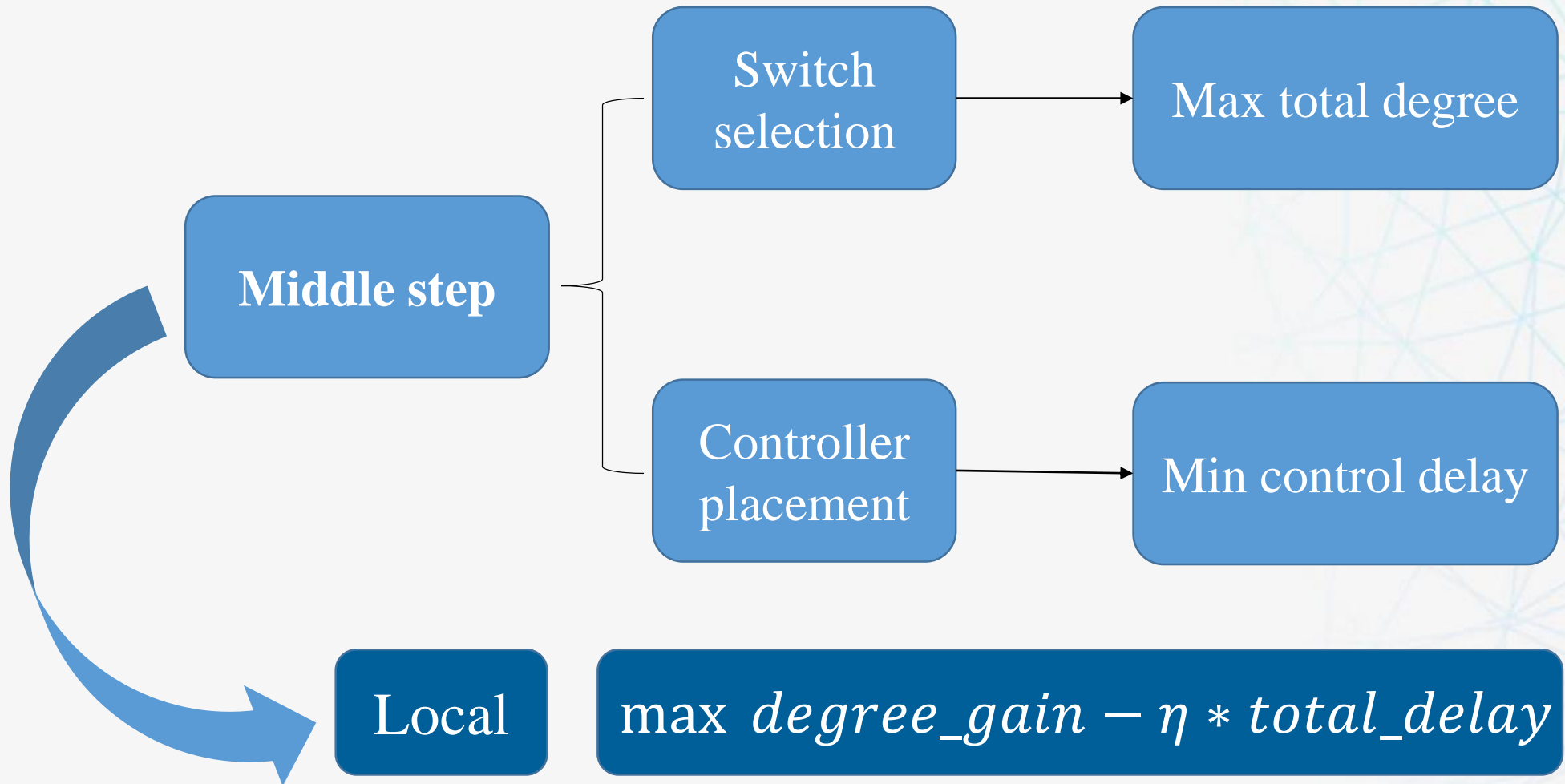
Last step  **Pure SDN**

- Minimizing the delay



Pure SDN

Solution



Solution

Last step: min total delay

Global optimal position for controllers in pure SDN

Punish the non-global optimal position

Global

min total punishment



Solution

Local:
max degree gain
min total delay



max $degree_gain - \eta * total_delay$



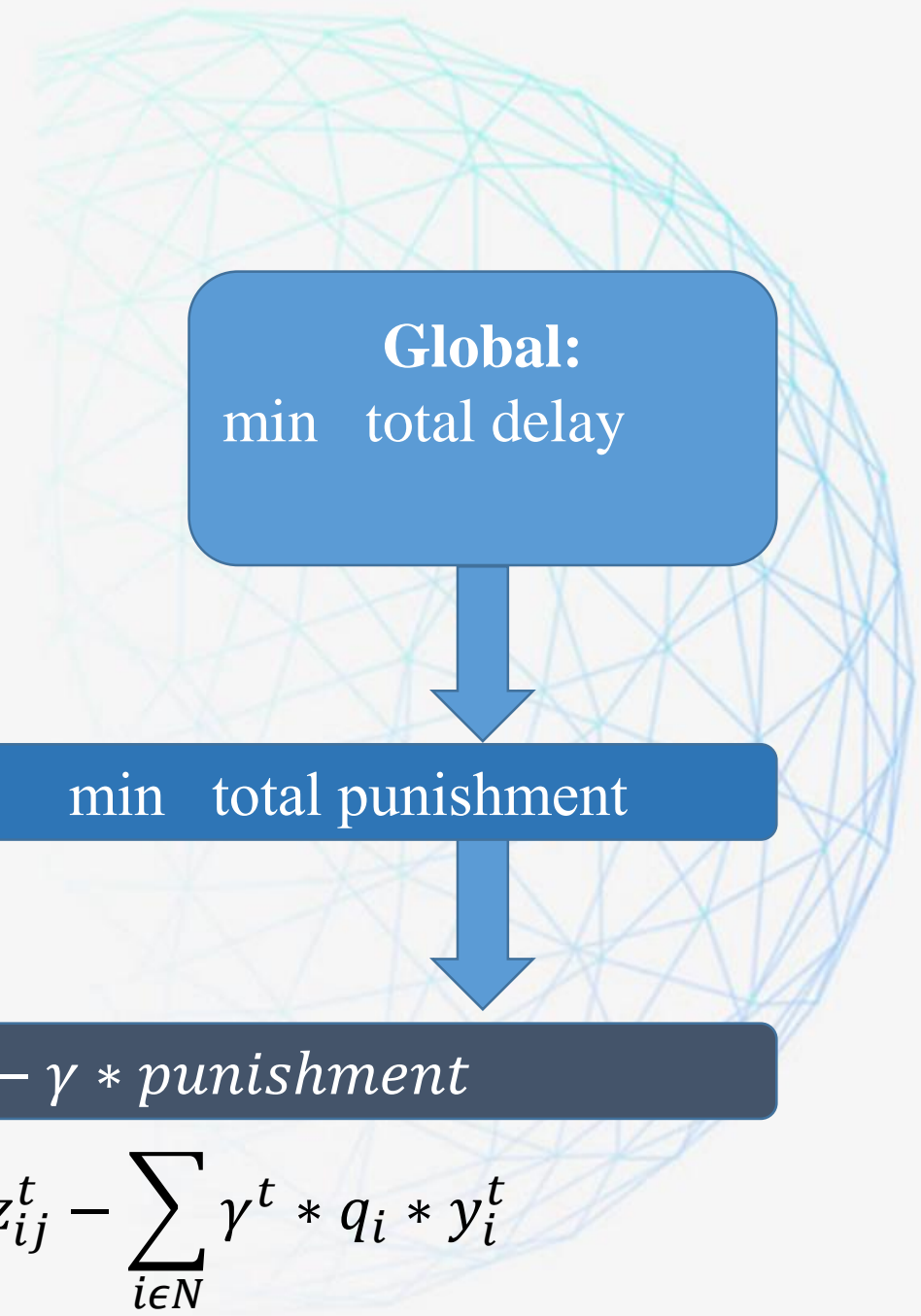
max $degree_gain - \eta * total_delay - \gamma * punishment$

$$\max \sum_{i \in N} \beta^t * d_i * x_i^t - \eta * \sum_{i, j \in N} \omega_{ij} * z_{ij}^t - \sum_{i \in N} \gamma^t * q_i * y_i^t$$

Global:
min total delay



min total punishment



Evaluation

- Dataset

- Atmnet –Topology Zoo
- 21 nodes and 22 edges

- Compared methods

- Naive deployment:

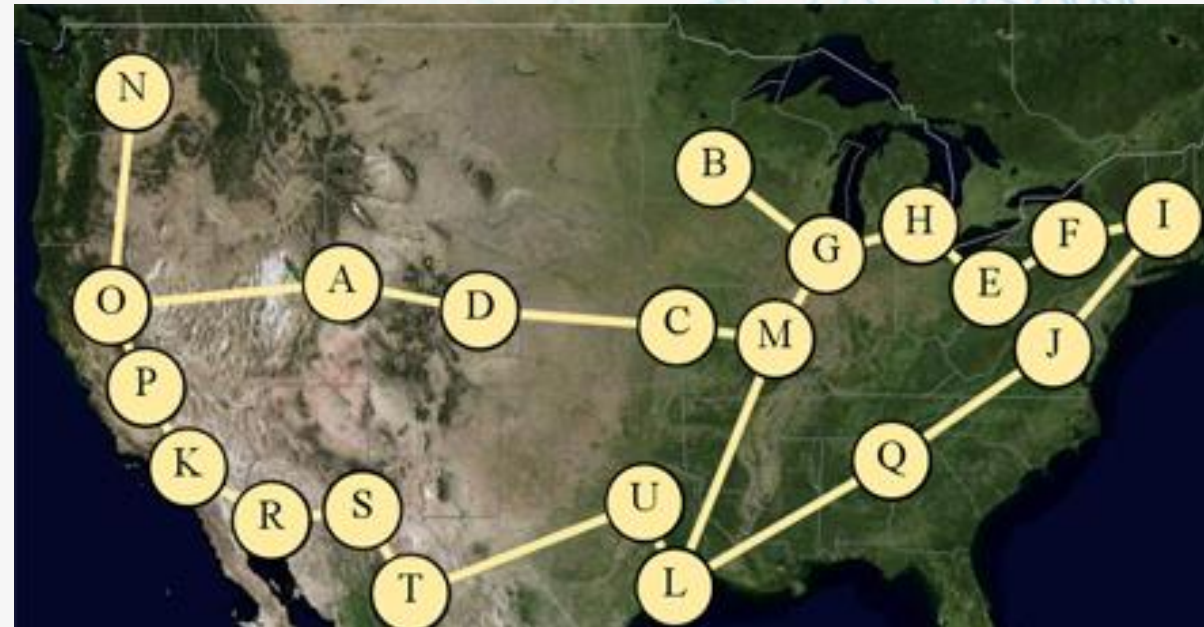
First pick the switches in the degree descending order, then deploy the controllers in the sub SDN network to minimize control delay.

- Joint deployment:

To maximize the degree gain and minimize the control delay simultaneously in each step.

- Global deployment:

To maximize the degree gain, minimize control delay, and minimize the penalty simultaneously in each step.



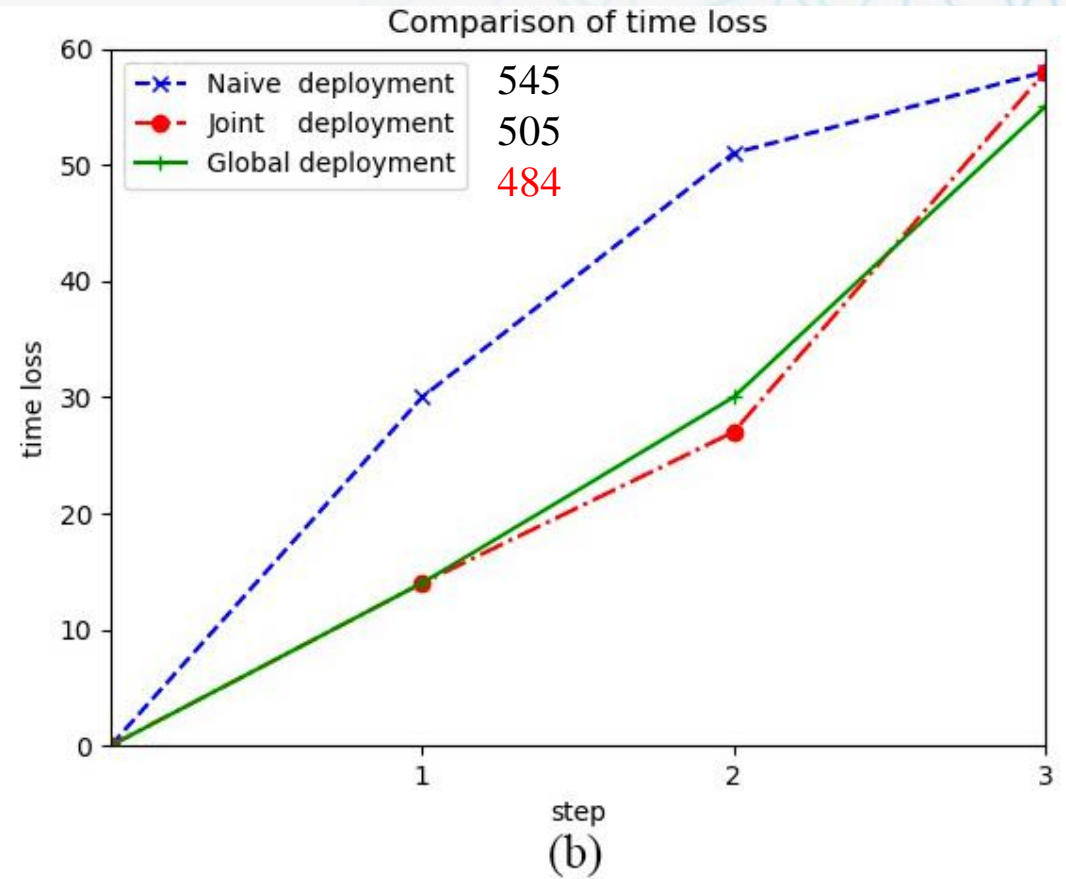
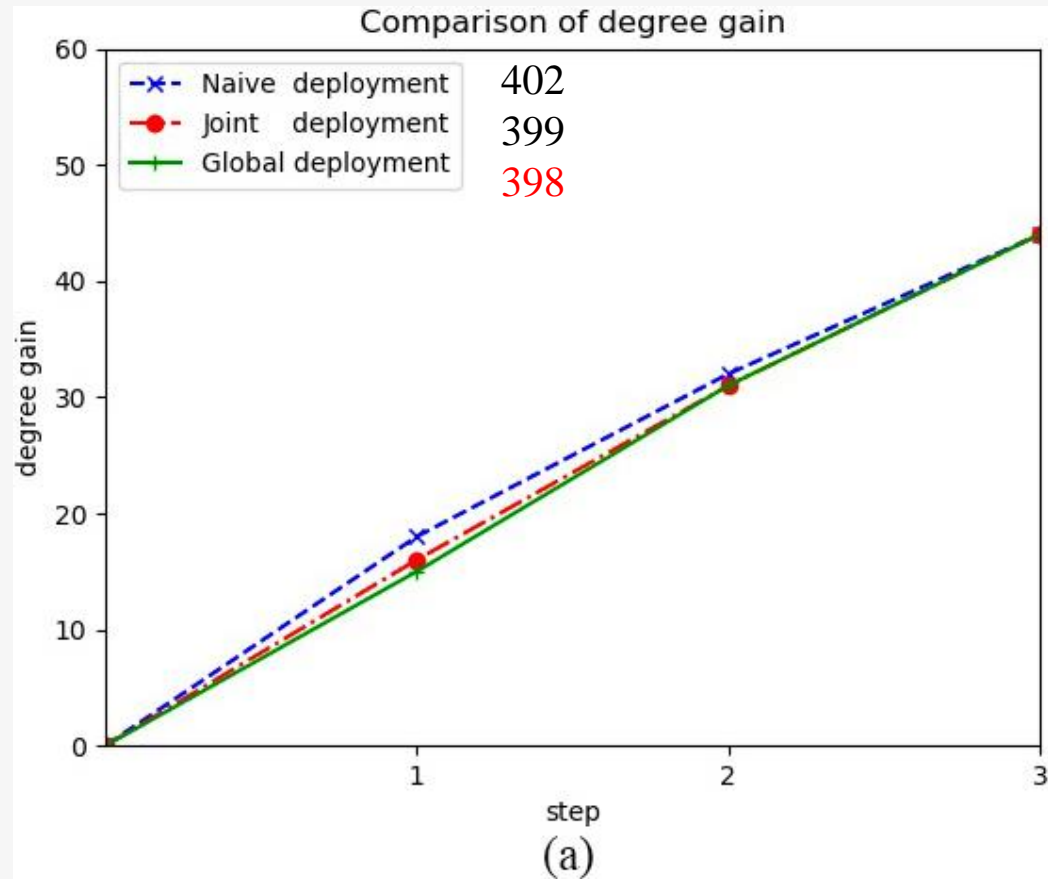
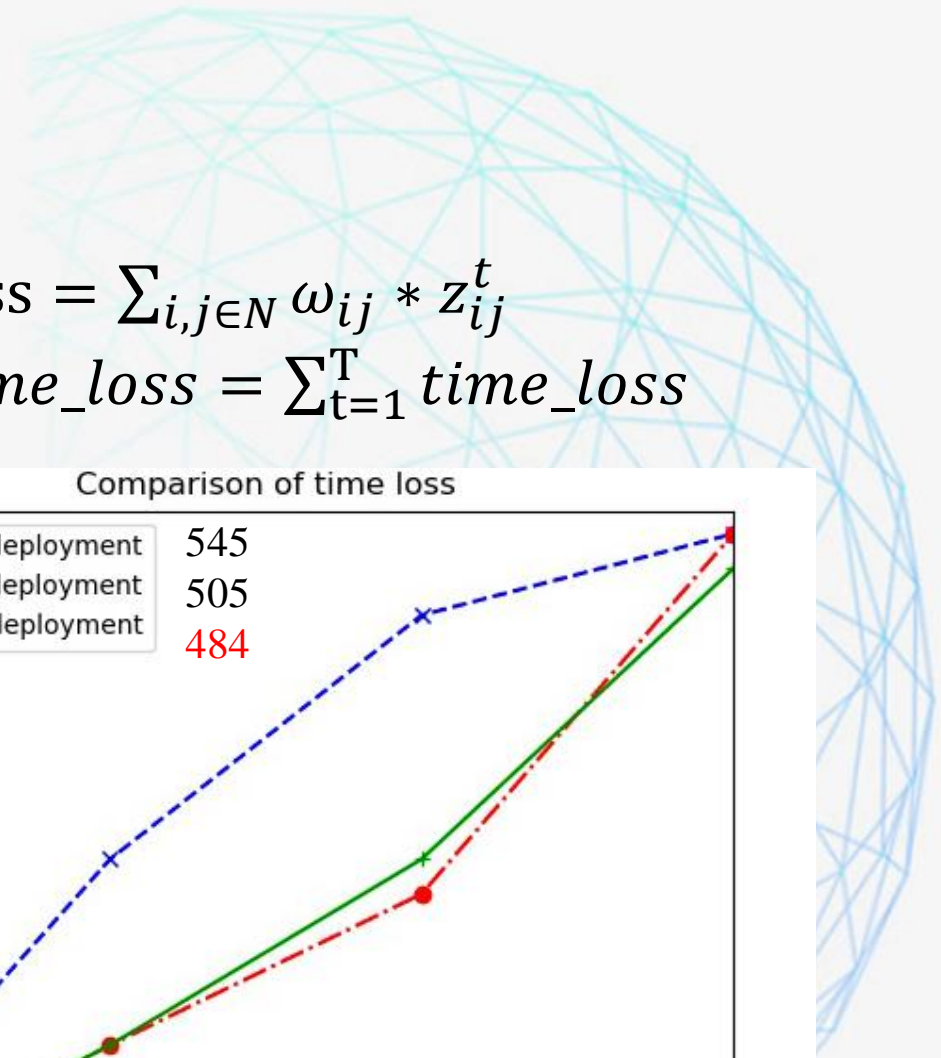
Evaluation

$$\text{degree_gain} = \sum_{i \in N} d_i * x_i^t$$

$$\text{total_degree_gain} = \sum_{t=1}^T \text{degree_gain}$$

$$\text{time_loss} = \sum_{i,j \in N} \omega_{ij} * z_{ij}^t$$

$$\text{total_time_loss} = \sum_{t=1}^T \text{time_loss}$$



Conclusion

- Contribution
 - **Jointly** deploy controllers and upgrade switches at each time step in the **whole migration process**.
 - Considers the **inconsistence** of middle steps and final step.
 - By introducing the **penalty item**, the optimization problem is transformed into solvable single-objective linear programming problem.
- Results
 - Our method could get a **tradeoff** between the **local** and **global** goals.





Thanks for your listening